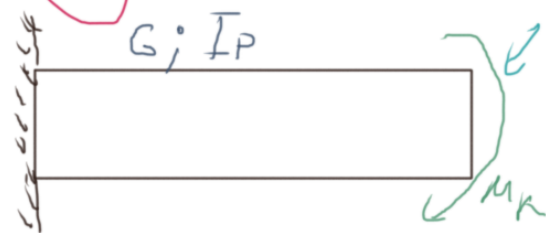


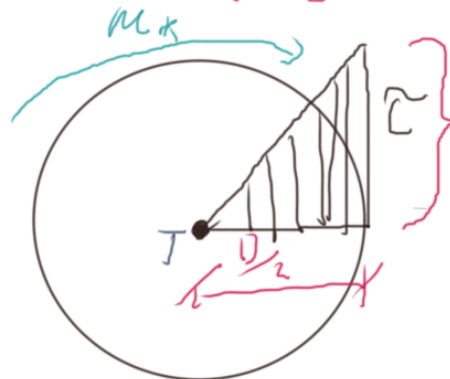
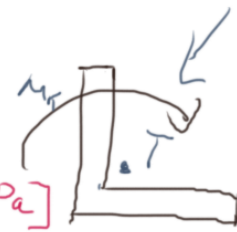
NA MĚNĚNÍ KRUŽEM
 - PRO KRUHOVÉ PRŮŘÍZY

→ COULOMBŮV ZÁKON

$$\tau = G \cdot \varphi$$



τ - SMYKOVÉ NAPĚTÍ [Pa]
 G - SMYKOVÝ MODUL [Pa]
 φ - ÚHEL ZKRUČENÍ [rad]



NAPĚTÍ PŘI KRUŽU

$$\tau(x; \rho) = \frac{M_K(x)}{I_P(x)} \cdot \rho$$

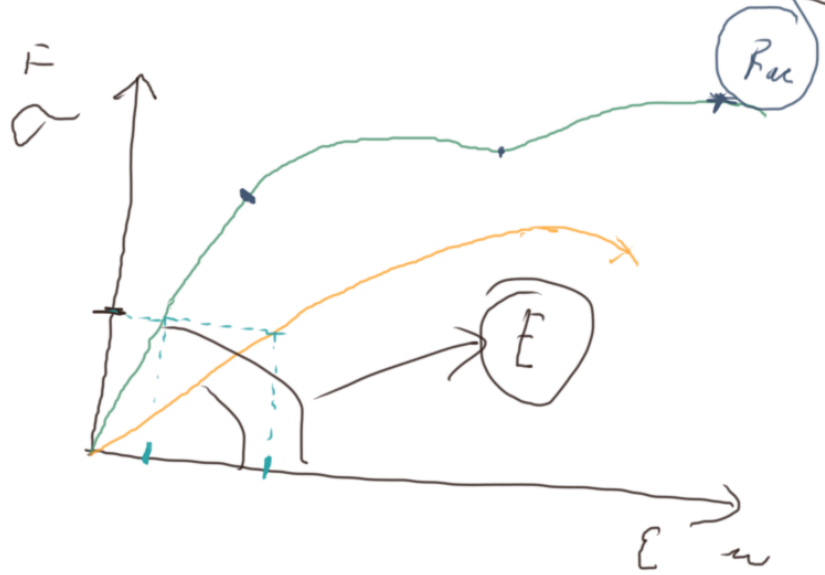
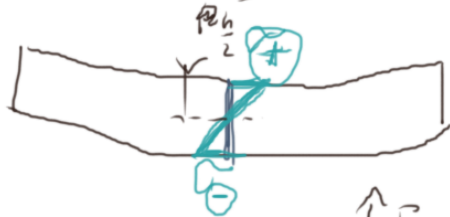
$$\tau_p \geq \tau_{max} = \frac{M_{Kmax}}{I_P} \cdot \frac{D}{2}$$

M_K - KRUČÍCÍ MOMENT [N.m]

I_P - POLÁRNÍ MOMENT SETŘAČNOSI



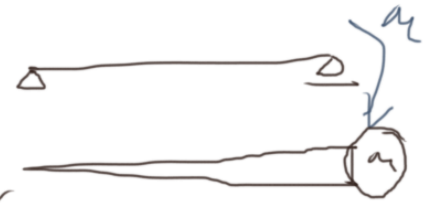
$$\sigma = \frac{M_{\max}}{I_y} \cdot \frac{h}{2}$$



DEFORMAČNÍ ENERGIJE

$$r_k = \frac{1}{2} \epsilon \cdot \rho$$

$$E = \int_V r_k dV = \frac{1}{2G \cdot I_P} \int_{(L)} M_k^2(x) dx \quad \Bigg| \quad E = \frac{1}{2E \cdot I_f} \int_{(L)} m^2(x) dx$$



FUNKCE ÚČRŮ ZKROUČENÍ

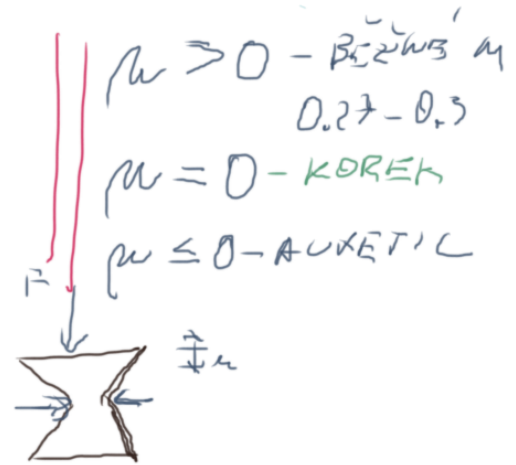
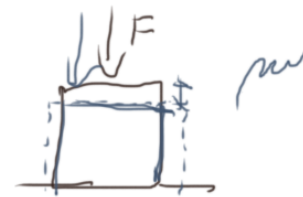
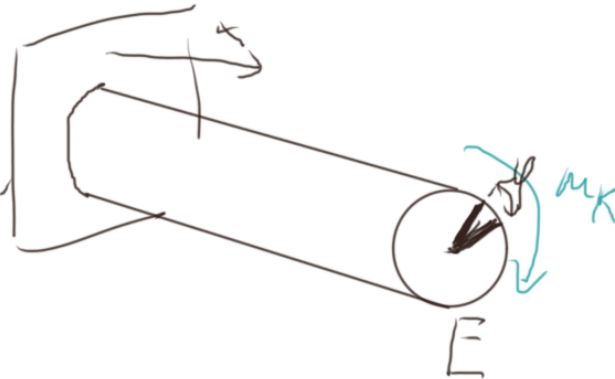
$$\varphi(x) = \frac{1}{G I_P} \int M_k(x)$$

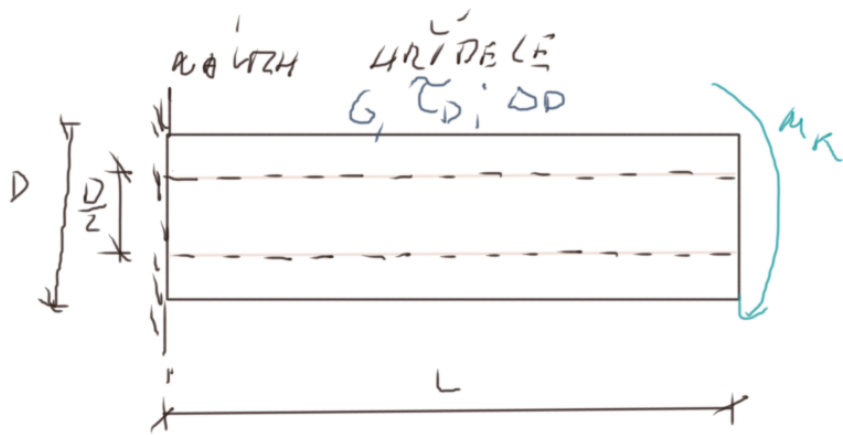
POMĚŘOVÁNÍ ÚKLOU ZKROUČENÍ

$$\Delta = \frac{d\varphi}{dx}$$

YMP

$$E \cdot G \rightarrow G = \frac{E}{2(\nu + 1)}$$





Δαño: L
M_K



ζ_D - ΠΕΛΛΟΣΤΑΤΗ ΡΟΘΑΙΝΑΚΑ
 Δ_D - ΤΟΧΟΣΤΑΤΗ ΡΟΘΑΙΝΑΚΑ

D - ΛΕΒΑΝΑΤΗ

ΠΕΛΛΟΣΤΑΤΗ ΡΟΘΑΙΝΑΚΑ

$$\zeta_D \geq \zeta = \frac{M_K}{I_P} \cdot \frac{D_0}{2}$$

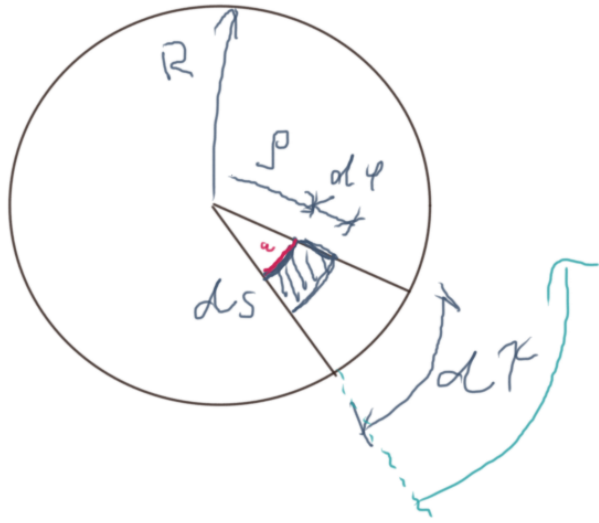
$$I_P = \frac{\pi}{32} \cdot D_0^4 - \frac{\pi}{32} \left(\frac{D_0}{2} \right)^4 = \frac{15\pi}{512} D_0^4$$

$$\zeta = \frac{M_K}{\frac{15\pi}{512} D_0^4} \cdot \frac{D_0}{2} = \frac{256 \cdot M_K}{15\pi \cdot D_0^3}$$

$$\Delta_D \geq \Delta = \frac{M_K}{G \cdot I_P} = \frac{512 M_K}{15\pi \cdot G \cdot D_0^4} \rightarrow D_0 \geq \sqrt[4]{\frac{512 M_K}{15\pi G \cdot \Delta}}$$

$$D_0 \geq \sqrt[3]{\frac{256 M_K}{15\pi \zeta}}$$

$$D = \max \{ D_0, D_0 \}$$



$$\bar{I}_p = \int_{(S)} \rho^2 \cdot dS$$

$$dS = \rho \cdot d\tau \cdot d\varphi$$

$$\bar{I}_p = \int_{(S)} \rho^3 \cdot d\tau \cdot d\varphi$$

$$\bar{I}_p = \int_0^R \rho^3 \frac{dS}{d\tau} =$$

$$d\tau = \frac{a}{\rho} \quad \begin{array}{l} dS = a \cdot d\varphi \\ dS = d\tau \cdot \rho \cdot d\varphi \end{array}$$

$$R = \frac{D}{2}$$

$$\frac{R^4}{4} \cdot 2\pi = \frac{1}{32} \pi D^4$$

$$R_K = 4M_K - M_{K2} = 3M_K$$

$$I_{P2} = \frac{I_P}{2}$$

- 1) MAXIMALNI ÚHLÍČ ZKŘIVLENÍ
- 2) CÍLKOVÁ DRŽ P. 1.2.5.6.10

$$\varphi(x) = \int \frac{M(x)}{G I_P} dx$$

$$x_1 \in (0; l)$$

$$\varphi(x_1) = \int \frac{3M_K}{G I_P} dx_1 = \frac{3M_K}{G I_P} x_1 + C_1$$

$$\varphi(0) = 0 \rightarrow C_1 = 0$$

$$\varphi(x_1) = \frac{3M_K}{G I_P} \cdot x_1 \quad \varphi(l) = \frac{3M_K \cdot l}{G \cdot I_P}$$

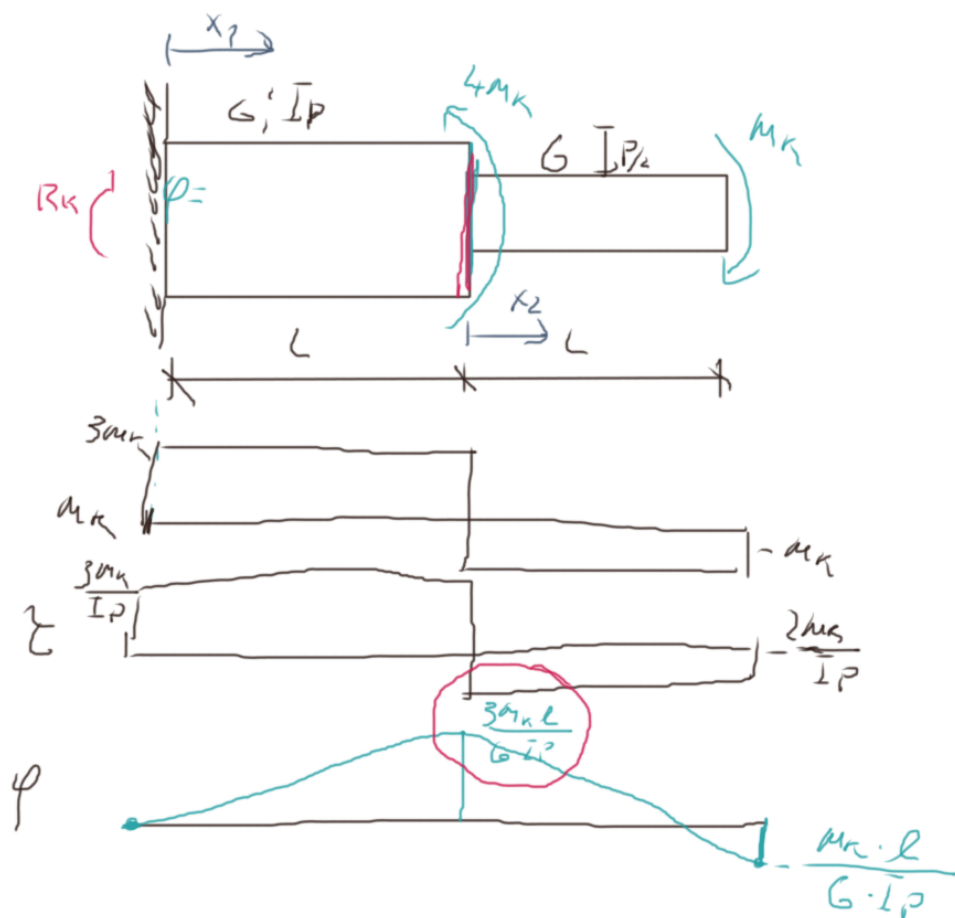
$$x_2 \in (0; l)$$

$$\varphi(x_2) = \int \frac{-M_K}{G \cdot I_{P2}} dx_2 = - \frac{2M_K}{G I_{P2}} \cdot x_2 + C_2$$

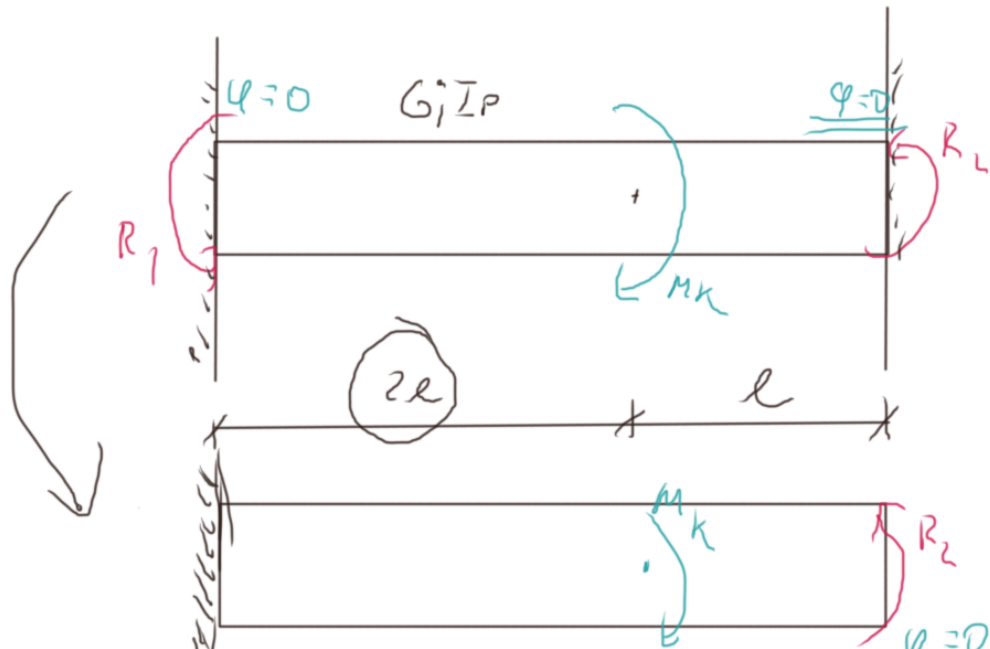
$$\varphi(l) = \frac{3M_K \cdot l}{G \cdot I_P}$$

$$\varphi(l) = - \frac{4M_K}{G I_P} \cdot l + \frac{3M_K}{G I_P}$$

$$\varphi(l) = - \frac{M_K \cdot l}{G I_P} \leftarrow$$



$$\begin{aligned}
 E &= \frac{1}{2GI_P} \int_0^l M_K^2(x) dx = \frac{1}{2GI_P} \int_0^l (3M_K)^2 dx + \frac{1}{2G \cdot I_{PK}} \int_0^l (-M_K)^2 dx = \\
 &= \frac{9M_K^2 l}{2GI_P} + \frac{M_K^2 l}{GI_P} = \frac{11M_K^2 \cdot l}{2G \cdot I_P}
 \end{aligned}$$



STANOVITE REAKCE R_1 a R_2

STATICKÉ PODMÍNKY

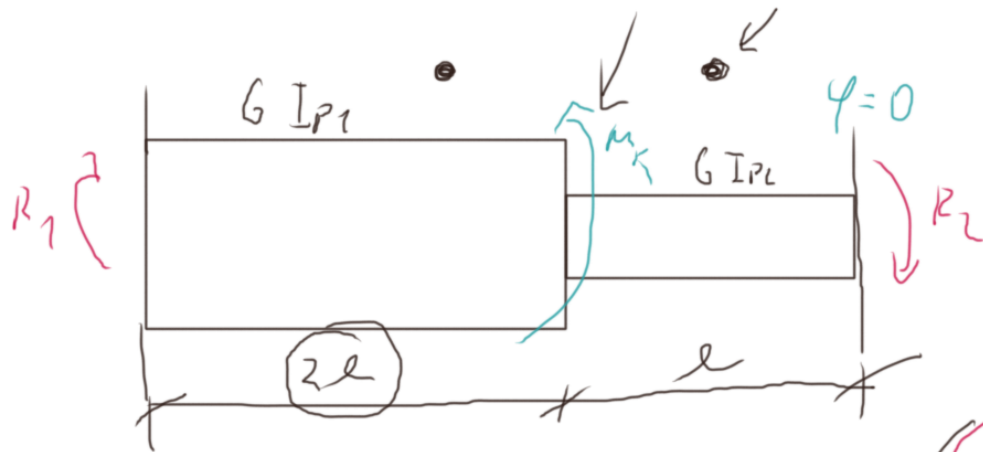
$$\hookrightarrow R_1 - M_k + R_2 = 0$$

$$\underline{\varphi(3l) = 0}$$

$$\varphi(3l) = 0 = \frac{M_k \cdot 2l}{6 I_p} - \frac{R_2 \cdot 3l}{6 I_p} = 0$$

$$\rightarrow R_2 = \frac{2}{3} M_k$$

$$\left[R_1 = \frac{1}{3} M_k \right]$$



$$R_1 + R_2 - M_k = 0$$

$$\varphi(3l) = 0 = \frac{M_k \cdot 2l}{G \cdot I_{p1}} - R_2$$

$$\left(\frac{l}{G I_{p2}} + \frac{2l}{G I_{p1}} \right) = 0$$

PODDAJNOŚĆ TORZNI J

$$\frac{1}{J} = \rho - \text{TUHOŚĆ TORZNI}$$



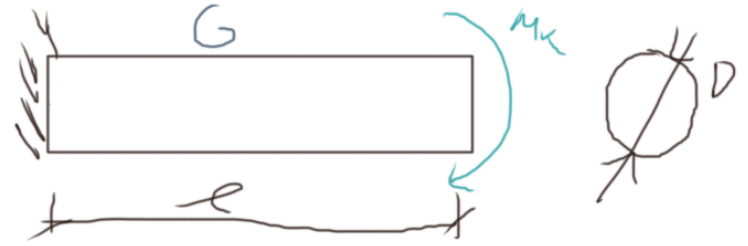
$$w(x) = \int \frac{F}{E \cdot A} dx$$

$$w(l) = \frac{Fl}{E \cdot A}$$

(u)



$$U = \int_0^l \frac{F^2}{2EA} dx = \frac{1}{2} \frac{F^2 l}{E \cdot A}$$



$$\varphi(x) = \int \frac{M_k}{G \cdot I_p} dx$$

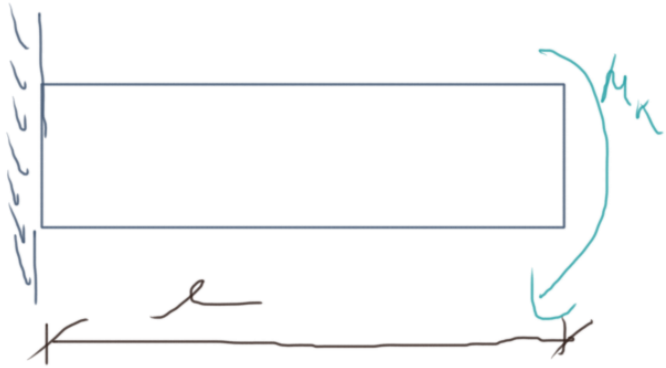
$$\varphi(l) = \frac{M_k \cdot l}{G I_p}$$

(\varphi)



$$U = \int_0^l \frac{M_k^2}{2 \cdot G I_p} dx = \frac{1}{2} \frac{M_k^2 l}{G \cdot I_p}$$





$$\varphi_{\max} = \frac{M_k l}{G I_P}$$

$$U = E = \frac{1}{2 G I_P} \int_0^l M_k^2 dx = \frac{M_k^2 l}{2 G I_P}$$

$$W = \frac{1}{2} M_k \cdot \varphi$$



$$U = W$$

$$\frac{M_k^2 l}{2 G I_P} = \frac{1}{2} M_k \cdot \varphi$$

$$\varphi = \frac{M_k l}{G \cdot I_P}$$